Writing Efficient Programs in Fortran, C and C++: Selected Case Studies

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Agenda

- „Common sense“ optimizations
  - Case Study: Optimization of a Monte Carlo spin system simulation
- Classic data access optimizations
  - Case Study: Optimization of kernel loops
  - Case Study: Optimization and parallelization of a Strongly Implicit Solver
- Advanced Parallelization
  - Case Study: Parallelization of a C++ sparse matrix-vector multiplication

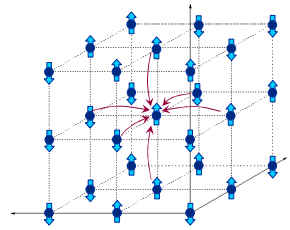
Case Study: Optimization of a Monte Carlo Spin System Calculation

Optimization of a Spin System Simulation: Model

- 3-D cubic lattice
- One variable („spin“) per grid point with values

  +1 or -1

- „Interaction“: Variables on neighbouring grid points prefer to have the same values



Optimization of a Spin System Simulation: Model

- Systems under consideration
  - 50·50·50=125000 lattice sites
  - 2^{125000} different configurations
  - Computer time: $2^{125000} \cdot 1\text{ ns} \sim 10^{37000}$ years
- Loophole: Monte Carlo simulation!
  Random choice of a subset of all configurations
- Memory requirement of original program ~ 1 MByte

Optimization of a Spin System Simulation: Original Code

- Program Kernel:

```
IA=IZ(KL,KM,KN)
IL=IZ(KLL,KM,KN)
IR=IZ(KLR,KM,KN)
IO=IZ(KL,KMO,KN)
IU=IZ(KL,KMU,KN)
IS=IZ(KL,KM,KNS)
IN=IZ(KL,KM,KNN)
```

Load neighbours of a random spin

calculate magnetic field

```
edelz=iL+iR+iU+iO+iS+iN

C     CRITERION FOR FLIPPING THE SPIN

      BF= 0.5d0*(1.d0+tanh(edelz/tt))
      IF(YHE.LE.BF) then
      iz(kl,km,kn)=1
      else
      iz(kl,km,kn)=-1
      endif
```

decide about spin orientation

Optimization of a Spin System Simulation: Code Analysis

- Profiling shows that
  - 30% of computing time is spent in the `tanh` function
  - Rest is spent in the line calculating `edelz`
- Why?
  - `tanh` is expensive by itself
  - Compiler fuses the spin loads and calculation of `edelz` into a single line
- What can we do?
  - Try to reduce the „strength“ of calculations (here `tanh`)
  - Try to make the CPU move less data
- How do we do it?
  - Observation: argument of `tanh` is always integer in the range -6..6 (`tt` is always 1)
  - Observation: Spin variables only hold values +1 or -1

Optimization of a Spin System Simulation: Making it Faster

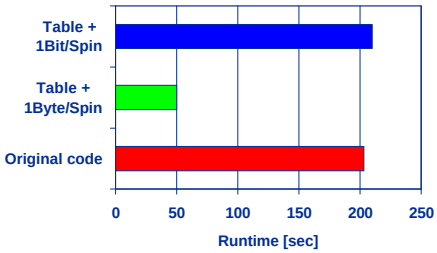
- Strength reduction by tabulation of `tanh` function

```
BF= 0.5d0*(1.d0+tanh_table(edelz))
```

  - Performance increases by 30% as table lookup is done with „lightspeed“ compared to `tanh` calculation
- By declaring spin variables with `INTEGER*1` instead of `INTEGER*4` the memory requirement is reduced to about ¼
  - Better cache reuse
  - Factor 2–4 in performance depending on platform
  - Why don‘t we use just one bit per spin?
    - Bit operations (mask, shift, add) too expensive ? no benefit
- Potential for a variety of data access optimizations
  - But: choice of spin must be absolutely random!

Optimization of a Spin System Simulation: Performance Results

- Pentium 4 (2.4 GHz)



Case Study: Optimization of Kernel Loops

Optimization of Kernel Loops

- Code from theoretical nuclear physics (three-nucleon interaction)
  - MPI code, typically 64 CPUs (8 nodes) on SR8000
- Original program performance on SR8000 (1 CPU): 26 MFlops
- Major part (98%) of compute time is attributed to code fragment with two simple loops:

```
do M = 1,IQM
   do K = KZHX(M),KZAHL
      F(K) = F(K)*S(MVK(K,M))
   enddo
enddo
```

1st loop: ≈ ¾ of time

```
do K = 1,KZAHL
   WERTT(KVK(K)) = WERTT(KVK(K))+F(K)
enddo
```

2nd loop: ≈ ¼ of time

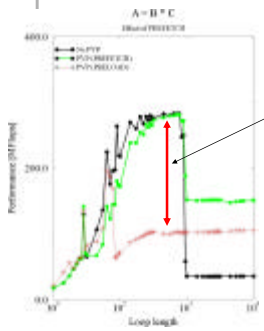
Optimization of Kernel Loops: Helping the Compiler

- SR8000 compiler with highest optimization chooses the following pseudo-vectorization strategy:
  - Prefetch for `MVK()`, `F()` and `KVK()`
  - Preload for `S()` and `WERTT()`
  - Outer loop unrolling of first loop impossible due to dependencies
  - Unrolling of second loop useless due to possible dependencies
- Important facts about the data structures:
  - `IQM` is small (typically 9)
  - Entries in `KZHX()` are sorted in ascending order
  - Length of `S()` is small (between 100 and 200), array fits in cache
  - `KZAHL` is typically a couple of 1000s
  - Length of `WERTT()` is very small (1 in the worst case), fits in cache
- First aid: disable pseudo-vectorization for `S()` and `WERTT()`
  - ® acceleration to 77 MFlops!

Optimization of Kernel Loops: Why preload is not always beneficial

- Preload must be issued…
  - for every input stream in the loop that is eligible for it
  - for every iteration of the unrolled loop
- Significant overhead for data that is already in cache
- Why is prefetch not as bad for in-cache data?
  - Prefetch only necessary for each 16th data element in each stream (cache line size is 128 bytes)
  - This rate is achieved by the appropriate amount of unrolling
    - unrolling avoids unnecessary prefetches
- Preload might be better for strided access
  - The larger the stride, the less efficient is prefetch

Optimization of Kernel Loops: Why preload is not always beneficial

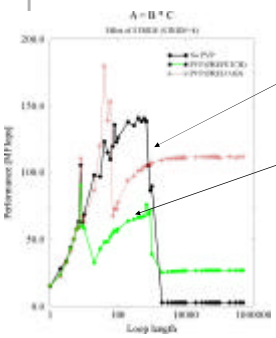


- Example: Vector product

```
A(1:N)=B(1:N)*C(1:N)
```

- In-cache preload penalty: factor 3
  - No cache reuse!
  - One preload per iteration
- In-cache prefetch penalty: maybe 10%
  - Just one prefetch every 16 iterations
- Out-of-cache preload: better than nothing, but much worse than (consecutive) prefetch

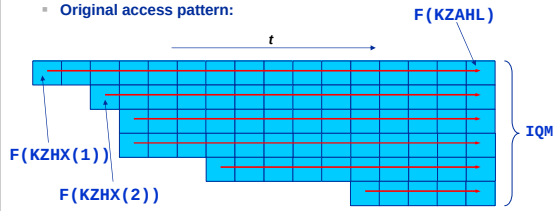
Optimization of Kernel Loops: Why preload is not always beneficial



- Strided access (stride 8): Bad reuse of prefetched data
  - Effective cache size is only 1/8 of real size
  - One prefetch every other iteration
    - CPU running out of memory references!
- Stride does not affect performance of preload streams

Optimization of Kernel Loops: Data Access Transformations, First Loop

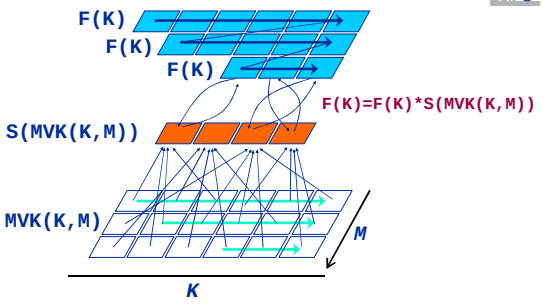
- Is there more potential for optimization?
  - Try to enable unrolling of outer loop!
  - Original access pattern:



- Initially: no outer loop unrolling possible, i.e. no potential for register reuse
  - F() is loaded many times from memory (or cache)

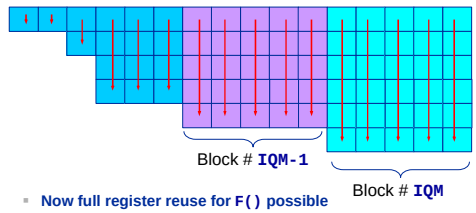
Optimization of Kernel Loops: Data Access Transformations, First Loop

- Visualization of data access



Optimization of Kernel Loops: Data Access Transformations, First Loop

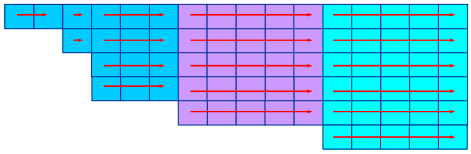
- Naïve optimization: "pseudo-loop-interchange"
  - New access pattern: introduce new outer loop level (blocking), interchange middle and inner loops



- Now full register reuse for F() possible
- F() is loaded only once from memory
- Downside: small inner loop length

Optimization of Kernel Loops: Data Access Transformations, First Loop

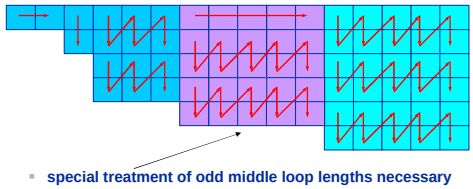
- Naïve optimization does not pay off with SR8000 and all Intel systems
  - Inner loop length too small
  - Even manual unrolling of middle (K) loop does not help
- Remedy: Retain a moderately large inner loop length but enable unrolling to improve Flop/Load quotient
  - Access pattern:



- Unrolling of middle loop now possible

Optimization of Kernel Loops: Data Access Transformations, First Loop

- Final access pattern:



- special treatment of odd middle loop lengths necessary
- SR8000 compiler now unrolls the middle loop further
  - overall unrolling factor of 48
  - moderate integer register spill
- Performance: » 87 MFlops

Optimization of Kernel Loops: Optimal SR8000 Code for First Loop

```
do M=1,IQM
  ISTART=KZHX(M)
  if(M.NE.IQM) then
    IEND=KZHX(M+1)-1
  else
    IEND=KZAHL
  endif
  IS=1
  if(mod(M,2).NE.0) then
    do MM=1,mod(M,2)
*voption nopreload(S)
*voption noprefetch(S)
      do K=ISTART,IEND
        F(K)=F(K)*S(MVK(K,IS))
      enddo
    enddo
    IS=IS+mod(M,2)
  endif
```

remainder loop

```
    do MM=IS,M,2
*voption nopreload(S)
*voption noprefetch(S)
      do K=ISTART,IEND
        F(K)=F(K)*S(MVK(K,MM))
 1                *S(MVK(K,MM+1))
      enddo
    enddo
  enddo
```

middle loop

Optimization of Kernel Loops: Data Access Transformations, Second Loop

- Problem: Data dependency prevents compiler from unrolling the loop (no improvement expected)
- Remedy: Unrolling pays off when the instances of the loop body write to different targets

```
do K=IS,KZAHL,2
  WERTT(KVK(K)) = WERTT(KVK(K)) + F(K)
  if(IM.lt.KVK(K)) IM=KVK(K)
  WERTT2(KVK(K+1)) = WERTT2(KVK(K+1)) + F(K+1)
  if(IN.lt.KVK(K+1)) IN=KVK(K+1)
enddo
```

remainder loop omitted!

calculation of length for reduction loop

```
IQ=max(IM,IN)
do K=1,IQ
   WERTT(K)=WERTT(K)+WERTT2(K)
enddo
```

reduction loop

- Final subroutine performance: » 94 MFlops
  - Whole program: 90 MFlops; MPI code performance doubled

Optimization of Kernel Loops: Architectural Issues

- MIPS R14000: Optimal strategy is the naïve optimization!
  - Original code performs about as well as fully optimized version on SR8000
    - no unnecessary preload attempts because there is no provision for preload
  - Good performance of short loops due to short pipelines
  - Compiler unrolls the middle loop automatically to make the loop body fatter
  - 2 instructions/cycle (very good!)
  - Final code on O3400 is about 50% faster than optimal version on SR8000

Optimization of Kernel Loops: Architectural Issues

- IA32: Optimal strategy is the same as for SR8000
  - Very limited FP register set, stack-oriented
  - Few integer registers
  - Long P4 pipeline, but good performance with short loops
    - due to special L1-ICache (decoded instructions)?
- IA64: Optimal strategy is the same as for SR8000
  - Very bad performance for naive strategy
  - Further unrolling (by 4) of middle loop helps
  - But: Naive optimization with middle loop unrolling (16-fold) is also very close to optimum
    - Also some benefit on IA32, but not that much

Optimization of Kernel Loops: Conclusions

- SR8000 is a RISC architecture, but has some particular features
  - Vectorization abilities
    - 16 outstanding prefetches
    - 128 outstanding preloads
  - Large bandwidth
  - Long FP pipelines
- Careful data stream analysis is more important on SR8000 than on other RISC systems
  - Sometimes PVP gets in the way of performance
- MIPS behaviour is as expected for typical RISC machine
- IA32/IA64 is still a mystery
  - Complicated architecture (CISC+RISC/EPIC), maybe compiler deficiencies

Case Study: Optimization and Parallelization of a Strongly Implicit Solver

CFD kernel: Strongly Implicit Solver

- CFD: Solving

  A x = b

  for finite volume methods can be done by Strongly Implicit Procedure (SIP) according to Stone
- SIP-solver is widely used:
  - LESOCC, FASTEST, FLOWSI (Institute of Fluid Mechanics, Erlangen)
  - STHAMAS3D (Crystal Growth Laboratory, Erlangen)
  - CADiP (Theoretical Thermodynamics and Transport Processes, Bayreuth)
  - ...
- SIP-Solver: 1) Incomplete LU-factorization
  2) Series of forward/backward substitutions
- Toy program available at: `ftp.springer.de:/pub/technik/peric` (M. Peric)

SIP-solver: Data Dependencies & Implementations

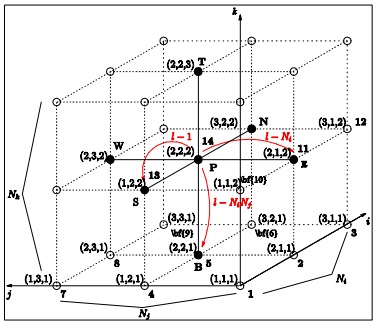
Basic data dependency:

`(i,j,k)` ⟵ `{(i-1,j,k);(i,j-1,k);(i,j,k-1)}`

Dominant part: Forward (and backward) Substitution!
Naive 3D version:

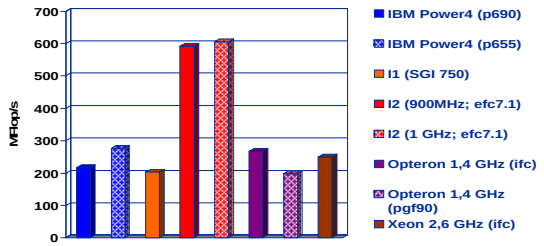
```
do k = 2 , kMax
   do j = 2 , jMax
      do i = 2 , iMax
        RES(i,j,k) =(RES(i,j,k) -LB(i,j,k)*RES(i,j,k-1) -
$          LW(i,j,k)*RES(i-1,j,k) -LS(i,j,k)* RES(i-1,j,k) )*
$          LP(i,j,k)
      enddo
   enddo
enddo
```


SIP-solver: Data Dependencies & Implementations



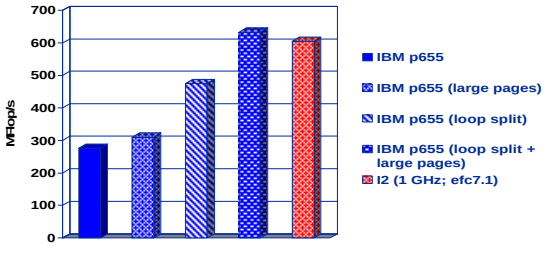
SIP-solver: Implementations & Single Processor Performance

size=91^3 (100 MB); naive implementation/compiler switches



SIP-solver: Implementations & Single Processor Performance

size=91³ (100 MB)
IBM improvements:
split single loop in 4 seperate loops; use large pages

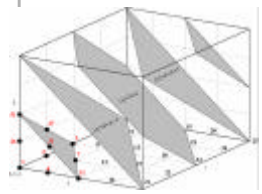


SIP-solver: Resolving Data Dependencies With Hyperplanes

Basic data dependency:
`(i,j,k) ⟵ {(i-1,j,k);(i,j-1,k);(i,j,k-1)}`

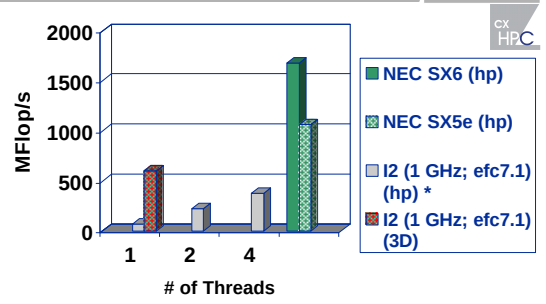
Define Hyperplane: **i+j+k=const**

- non-contiguous memory access
- shared memory parallelization /vectorization of innermost loop



```
do l=1,hyperplanes
  n=ICL(l)
  do m=n+1,n+LM(l)
    ijk=IJKV(m)
    RES(ijk)=(RES(ijk)-
$     LB(ijk)*RES(ijk-ijMax)-
$     LW(ijk)*RES(ijk-1)-
$     LS(ijk)*RES(ijk-iMax))
$     *LP(ijk)
  enddo
enddo
```


SIP Solver: SMP scalability (Hyperplane)



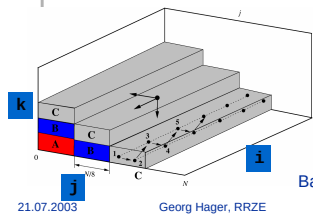
* !DIR$IVDEP

SIP-solver: Data Dependencies & Implementations

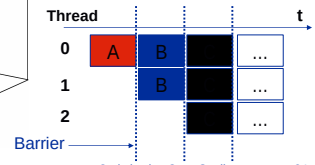
Basic data dependency:
`(i,j,k) ⟵ {(i-1,j,k);(i,j-1,k);(i,j,k-1)}`

3-fold nested loop (3D): **(i,j,k)**

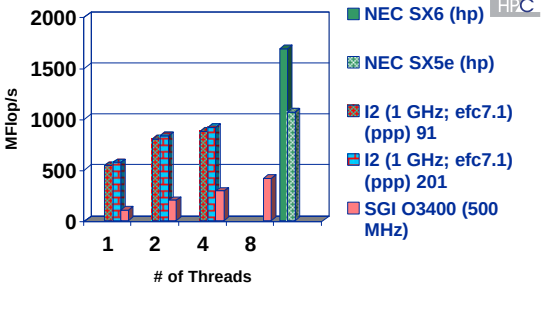
- Data locality, but recurrences
- No automatic shared memory parallelization by compiler, but OpenMP (except Hitachi SR8000: *Pipeline parallel processing*)



j-loop is being distributed:



SIP-solver: SMP scalability (Pipeline Parallel Processing)



SIP-solver: Implementations & Single Processor Performance

Benchmark:

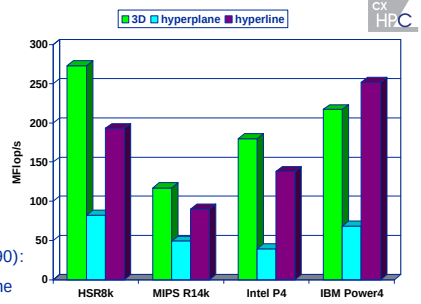
- Lattice: 91³
- 100 MB
- 1 ILU
- 500 iterations

HSR8k-F1:

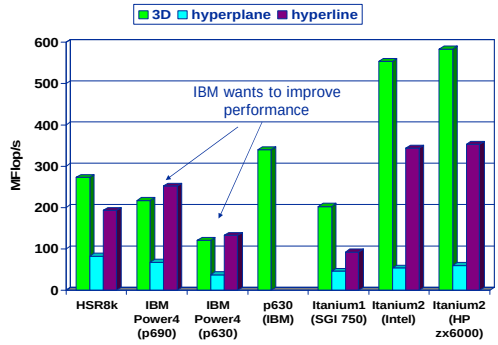
- unrolling up to 32 times

IBM Power4 (p690):

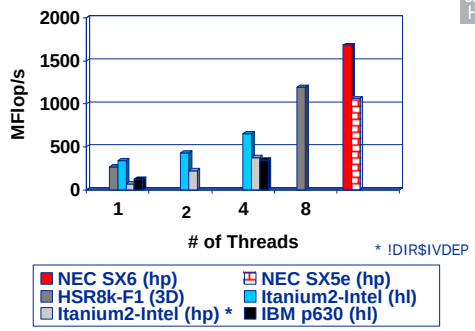
- 128 MB L3 cache accessible for 1 CPU



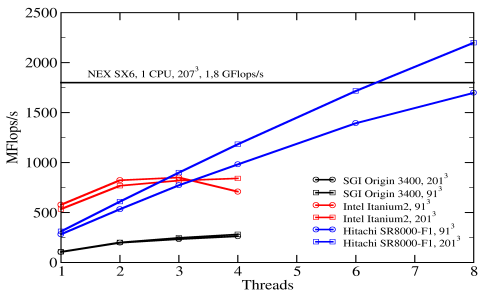
SIP-solver: Implementations & Single Processor Performance



SIP-solver: SMP scalability (Hyperplane & Hyperline)

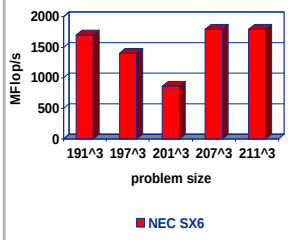


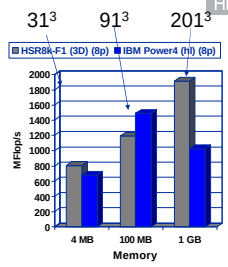
SMP scalability: Pipeline Parallel Processing (3D)



SIP-solver: Problem Sizes & Performance

Varying problem size





Be careful on vector systems when choosing memory layout!

Be careful with cache effects on IBM p690!

Case Study: Parallelization of a Sparse MVM in C++

Sparse MVM Procedure in DMRG

- DMRG
  - Density-Matrix Renormalization Group Algorithm
  - Used for solving quantum problems in solid state physics and theoretical chemistry
  - Alternative to expensive (resource-consuming) Exact Diagonalization
- Core of DMRG: Sparse matrix-vector multiplication (in Davidson diagonalization)
  - Dense matrices as matrix and vector components
  - Dominant operation at lowest level: dense matrix-matrix multiply (use optimized Level 3 BLAS!)
- Parallelization approaches:
  - Use parallel BLAS (no code changes)
  - Parallelize sparse MVM using OpenMP

DMRG: Potential Parallelization approaches

Implementation of sparse MVM - pseudocode

$$H\psi = \sum_{\alpha} \sum_{k} A_k^{\alpha} \psi_{R(k)} \left[B^{\mathrm{T}}\right]_k^{\alpha}$$

```
// W: wavevector ; R: result
for (a=0; a < number_of_hamiltonian_terms; a++) {      Parallel loop !?

   term = hamiltonian_terms[a];

   for (k=0 ; k < term.number_of_blocks; k++) {        Parallel loop !?

      li = term[k].left_index;
      ri = term[k].right_index;

      temp_matrix = term[k].B.transpose() * W[ri];

      R[li] += term[k].A * temp_matrix;

   }
}
```

Data dependency !

Matrix-Matrix-Multiply (Parallel DGEMM ?!)

DMRG: Potential Parallelization approaches

1. **Linking with parallel BLAS (DGEMM)**
   - Does not require restructuring of code
   - Significant speed-up only for large (transformation) matrices (A ,B)
2. **Shared-Memory parallelization of outer loops**
   - Chose OpenMP for portability reasons
   - Requires some restructuring & directives
   - Speed-Up should not depend on size of (transformation) matrices

Expected maximum speed-up for total program:

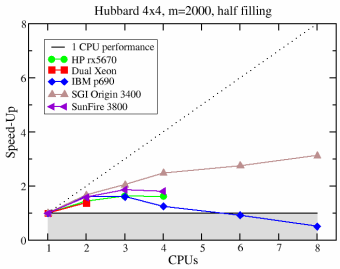
- if MVM is parallelized only: ~6 - 8
- if also Davidson algorithm is parallelized: ~10

MPI parallelization

- Requires complete restructuring of algorithm

DMRG: Linking With Parallel BLAS

- Useless on IBM for #CPU > 4
- Best scalability on SGI (Network, BLAS implementation)
- Dual processor nodes can reduce elapsed runtime by about 30 %
- Speedup is also strongly dependent on problem parameters



DMRG: OpenMP Parallelization

- Parallelization of innermost k loop: Scales badly
  - loop too short
  - collective thread operations within outer loop
- Parallelization of outer a loop: Scales badly
  - even shorter
  - load imbalance (trip count of k loop depends on a)
- Solution:
  - "Fuse" both loops (a & k)
  - Protect write operation R[li] with lock mechanism
  - Use list of OpenMP locks for each block li

DMRG: OpenMP Parallelization

Implementation of parallel sparse MVM – pseudocode (prologue loops)

```
// store all block references in block_array
ics=0;
for (a=0; a < number_of_hamiltonian_terms; a++) {
   term = hamiltonian_terms[a];
   for (k=0 ; k < term.number_of_blocks; k++) {
      block_array[ics]=&term[q];
      ics++;
   }
}
icsmax=ics;

// set up lock lists
for(i=0; i < MAX_NUMBER_OF_THREADS; i++)
   mm[i] = new Matrix // temp.matrix

for (i=0; I < MAX_NUMBER_OF_LOCKS; i++) {
   locks[i]= new omp_lock_t;
   omp_init_lock(locks[i]);
}
```


DMRG: OpenMP Parallelization

Implementation of parallel sparse MVM – pseudocode (main loop)

```
// W: wavevector ; R: result
#pragma omp parallel private(mymat, li, ri, myid, ics)
{
   myid = omp_get_thread_num();
   mytmat = mm[myid]; // temp thread local matrix

#pragma omp for
   for (ics=0; ics< icsmax; ics++) {

      li = block_array[ics]->left_index;
      ri = block_array[ics]->right_index;

      mytmat = block_array[ics]->B.transpose() * W[ri];

      omp_set_lock(locks[li]);
      R[li] += block_array[ics]->A * mytmat;
      omp_unset_lock(locks[li]);
   }
}
```

Fused (α,k) loop

Protect each block of result vector **R** with locks

DMRG: OpenMP Parallelization

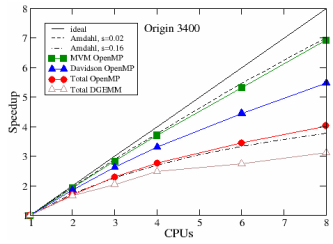
- The parallel code is compliant to the OpenMP standard
- However: NO system did compile and produce correct results with the initial MVM implementation!

IBM xlC V6.0	OpenMP locks prevent `omp for` parallelization	Fixed by IBM
Intel efc V7 ifc V7	Severe problems with orphaned `omp critical` directives in class constructors	Does not work
SUN forte7	Does not allow `omp critical` inside C++ classes!	Does not work (Forte 8 EA does work)
SGI MIPSpro 7.3.1.3m	Complex data structures can not be allocated inside `omp parallel` regions	Allocate everything outside loop

DMRG: OpenMP Parallelization

Scalability on SGI Origin

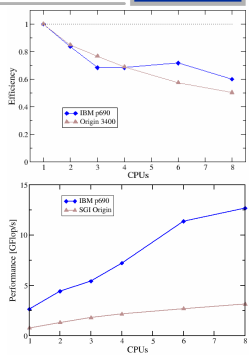
- `OMP_SCHEDULE=STATIC`
- OpenMP scales significantly better than parallel DGEMM
- Serial overhead in parallel MVM is only about 5%
- Still some parallelization potential left in program



DMRG: OpenMP Parallelization

Scalability & Performance: SGI Origin vs. IBM p690

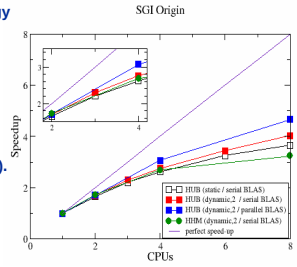
- Scalability is pretty much the same on both systems
- Single processor run and `OMP_NUM_THREADS=1` differ by approx. 5% on IBM
  - Hardly any difference on SGI
- Total performance
  1 * Power4 = 8 * MIPS
  8 * Power4 > 12 GFlop/s sustained!



DMRG: OpenMP Parallelization

Further improvement of total performance/scalability

- Chose best distribution strategy for parallel for loop: `OMP_SCHEDULE="dynamic,2"` (reduces serial overhead in MVM to 2%)
- Re-Link with parallel LAPACK /BLAS to speed-up density-matrix diagonalization (DSYEV). Good thing to do: `OMP_NESTED=FALSE`



Thank You!