



Summary of constitutive_ kalidinditwin subroutine

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This document contains information for constitutive_ kalidinditwin.f90 which is designed for HCP crystal. State variables in constitutive_ kalidinditwin are “slip resistance (s^α)”, “twin resistance (s^β)”, “cumulative shear strain (γ^α)”, and “twin volume fraction (f^β)”. Superscript α and β denote to 24 slip and 24 twin systems, respectively, in this entire document. Slip system has four different families (i.e., basal, prism, pyr $\langle a \rangle$ and pyr $\langle c+a \rangle$), and twin system has four different families (i.e., 2 tensile twins and 2 compressive twins). Table 1 lists slip/twin systems implemented in the subroutine.



			No. of slip system
slip system	basal	$\{0001\} \langle 1\bar{2}10 \rangle$	3
	prism	$\{10\bar{1}0\} \langle 1\bar{2}10 \rangle$	3
	pyr $\langle a \rangle$	$\{10\bar{1}1\} \langle 1\bar{2}10 \rangle$	6
	pyr $\langle c+a \rangle$	$\{10\bar{1}1\} \langle 2\bar{1}\bar{1}3 \rangle$	12
twin system	tensile (T1)	$\{10\bar{1}2\} \langle \bar{1}011 \rangle$	6
	compressive (C1)	$\{11\bar{2}2\} \langle 11\bar{2}3 \rangle$	6
	tensile (T2)	$\{11\bar{2}1\} \langle \bar{1}\bar{1}26 \rangle$	6
	compressive (C1)	$\{10\bar{1}1\} \langle 10\bar{1}2 \rangle$	6

Table 1: Implemented deformation mechanisms in α -Ti

1 Kinetics

Shear strain rate due to slip is described by following equation [1, 2]:

$$\dot{\gamma}^{\alpha} = \dot{\gamma}_o \left| \frac{\tau^{\alpha}}{s^{\alpha}} \right|^n \text{sign}(\tau^{\alpha}) \quad (1)$$

, where $\dot{\gamma}^{\alpha}$; shear strain rate, $\dot{\gamma}_o$; reference shear strain rate, τ^{α} ; resolved shear stress on the slip system, n ; hardening coefficient, and s^{α} ; slip resistance.

Twin volume fraction rate is described by following equation [1, 2]:

$$\dot{f}^{\beta} = \frac{\dot{\gamma}_o}{\gamma^{\beta}} \left| \frac{\tau^{\beta}}{s^{\beta}} \right|^n \mathcal{H}(\tau^{\beta}) \quad (2)$$

, where \dot{f}^{β} ; twin volume fraction rate, $\dot{\gamma}_o$; reference shear strain rate, γ^{β} ; shear strain due to twin, τ^{β} ; resolved shear stress on the twin system, and s^{β} ; twin resistance. \mathcal{H} is Heaviside function.

2 Structure Evolution

In this present section, we attempt to show how we establish the relationship between the evolution of slip/twin resistance and the evolution of shear strain/twin volume fraction.

2.1 Interaction matrix.

Conceptual relationship between the evolution of state and kinetic variables is shown in Equation 3.

$$\begin{bmatrix} \dot{s}^{\alpha} \\ \dot{s}^{\beta} \end{bmatrix}_{48 \times 1} = M_{48 \times 48} \begin{bmatrix} \dot{\gamma}^{\alpha} \\ \dot{f}^{\beta} \end{bmatrix}_{1 \times 48} \quad (3)$$

$M_{48 \times 48}$ consists of four interaction type matrices; i) slip-slip interaction type matrix ($M_{slip-slip}$), ii) slip-twin interaction type matrix ($M_{slip-twin}$), iii) twin-slip interaction type matrix ($M_{twin-slip}$), and iv) twin-twin interaction type matrix ($M_{twin-twin}$). Each interaction type matrix is 24×24 matrix.

$$M_{48 \times 48} = \begin{bmatrix} M_{slip-slip} & M_{slip-twin} \\ M_{twin-slip} & M_{twin-twin} \end{bmatrix} \quad (4)$$

Detailed interaction type matrices in Equation 4 will be further discussed in the following Section.

2.2 Interaction type

Following sections are separated into four based on each interaction type matrix alluded. Numbers in Tables 2, 3, 4, and 5 denote the type of interaction between deformation systems (The first column vs. The first row).

2.2.2 Slip-Twin interaction type

- There are 16 types of slip-twin interaction in Table 3.
- Meaning of T1, C1, T2, C2 is listed in Table 1.
- Actual slip-twin interaction matrix, $M_{slip-twin}$, is listed in Equation 6.

	T1	C1	T2	C1
basal	1	2	3	4
prism	5	6	7	8
pyr <a>	9	10	11	12
 a <c+a>	13	14	15	16

Table 3: Slip-twin interaction type

$$M_{slip-twin} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix} \quad (6)$$

2.2.3 Twin-Slip interaction type

- There 16 types of twin-slip interaction in Table 4.
- Meaning of T1, C1, T2, C2 is listed in Table 1.
- Actual twin-slip interaction matrix, $M_{twin-slip}$, is listed in Equation 7.

	basal	prism	pyr <a>	pyr <c+a>
T1		2	3	4
C1		6	7	8
T2	9	10	11	12
C2	13	14	15	16

Table 4: Twin-slip interaction type

$$M_{twin-slip} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{bmatrix} \quad (7)$$

2.3 Prefactor (nonlinear factor)

2.3.1 Prefactors for slip resistance (s^α); $M_{slip-slip}$ and $M_{slip-twin}$ [2]

$M_{slip-slip}$ and $M_{slip-twin}$ use for slip resistance evolution (\dot{s}^α). Equation 9 is for a slip resistance rate evolution. This currently shows the prefactor for slip-slip interaction matrix, $M_{slip-slip}$.

$$[\dot{s}^\alpha]_{24 \times 1} = h_s^\alpha \left(1 - \frac{s^\alpha}{S_s^\alpha}\right) M_{slip-slip} [\dot{\gamma}^\alpha]_{1 \times 24} \quad \text{or} \quad \dot{s}^\alpha = h_s^\alpha \left(1 - \frac{s^\alpha}{S_s^\alpha}\right) \sum_l^{N^S} \dot{\gamma}^l \quad (9)$$

, where h_s^α and S_s^α represent hardening rate and saturation slip resistance for slip system, respectively. N^S is the total number of slip system, 24. h_s^α and S_s^α depend on total twin volume fraction as describing in Equations 10 and 11, respectively. Thus, deformation twin and slip interaction is indirectly implemented in Equation 9.

$$h_s^\alpha = \begin{cases} h_{so}^{bas} \left(1 + C \left(\sum_\beta f^\beta\right)^b\right) & \text{if } \alpha \in \text{basal} \\ h_{so}^{pri} \left(1 + C \left(\sum_\beta f^\beta\right)^b\right) & \text{if } \alpha \in \text{prism} \\ h_{so}^{pyr<a>} \left(1 + C \left(\sum_\beta f^\beta\right)^b\right) & \text{if } \alpha \in \text{pyr} < a > \\ h_{so}^{pyr<c+a>} \left(1 + C \left(\sum_\beta f^\beta\right)^b\right) & \text{if } \alpha \in \text{pyr} < c + a > \end{cases} \quad (10)$$

, where h_{so}^α presents the hardening rate without twin volume fraction (i.e., $\left(\sum_\beta f^\beta = 0\right)$), and b is exponent to control the effect of twin volume fraction on the hardening rate. C is coefficient for twin effect.

$$s_s^\alpha = \begin{cases} s_{so}^{bas} + s_{pr} \left(\sum_\beta f^\beta\right)^{0.5} & \text{if } \alpha \in \text{basal} \\ s_{so}^{pri} + s_{pr} \left(\sum_\beta f^\beta\right)^{0.5} & \text{if } \alpha \in \text{prism} \\ s_{so}^{pyr<a>} + s_{pr} \left(\sum_\beta f^\beta\right)^{0.5} & \text{if } \alpha \in \text{pyr} < a > \\ s_{so}^{pyr<c+a>} + s_{pr} \left(\sum_\beta f^\beta\right)^{0.5} & \text{if } \alpha \in \text{pyr} < c + a > \end{cases} \quad (11)$$

, where s_{so}^α presents the saturation slip resistance without twin volume fraction (i.e., $\left(\sum_\beta f^\beta = 0\right)$), and s_{pr} is coefficient.

Slip-twin interaction matrix, $M_{slip-twin}$, has not been implemented with any prefactor yet. We need to decide whether Equations 10 and 11 remove from the current subroutine or not. Current way to implement the nonlinear factor for the effect of twin on \dot{s}^α is intertwined with Equation 9, so that it is hard to separate from it. Either we do not use $M_{slip-twin}$ or we need to provide additional prefactor for $M_{slip-twin}$ without using Equations 10 and 11.

2.3.2 Prefactors for twin resistance (\dot{s}^β); $M_{twin-slip}$ and $M_{twin-twin}$ [1]

$M_{twin-slip}$ and $M_{twin-twin}$ use for twin resistance evolution (\dot{s}^β). The first part in Equation 12 ($\dot{s}^\beta_{twin-twin}$) is twin-twin interaction contribution to twin resistance evolution, and the second part in Equation 12 ($\dot{s}^\beta_{twin-slip}$) is twin-slip interaction contribution to twin resistance evolution. Equations for each contribution is listed in Equations 13 and 14.

$$\dot{s}^\beta = \dot{s}^\beta_{twin-twin} + \dot{s}^\beta_{twin-slip} \quad (12)$$

$$\left[\dot{s}^\beta_{twin-twin} \right]_{24 \times 1} = h_{tw} \left(\sum_m f^m \right)^d M_{twin-twin} \left[\gamma^\beta f^\beta \right]_{1 \times 24} \quad \text{or} \quad \dot{s}^\beta_{twin-twin} = h_{tw} \left(\sum_m f^m \right)^d \sum_k \gamma^k f^k \quad (13)$$

,where h_{tw} and d are coefficients for twin-twin contribution. γ^β is shear strain for each twin system.

$$\left[\dot{s}^\beta_{twin-slip} \right]_{24 \times 1} = h_{tw-sl} \left(\sum_\alpha \gamma^\alpha \right)^e M_{twin-slip} \left[\dot{\gamma}^\alpha \right]_{1 \times 24} \quad \text{or} \quad \dot{s}^\beta_{twin-slip} = h_{tw-sl} \left(\sum_\alpha \gamma^\alpha \right)^e \sum_k \dot{\gamma}^k \quad (14)$$

,where h_{tw-sl} and e are coefficients for twin-slip contribution.



3 Material Parameters (Material Configuration file)

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## Parameters for phenomenological modeling (kalidinditwin)

s0_bas                65e6
s0_pri                22e6      Eqs. (1) & (9)
s0_pyr                50e6
s0_pyr_ca            50e6
-----
s0_t1                70e6
s0_c1                70e6      Eq (2)
s0_t2                250e8
s0_c2                250e8
-----
s_sat_bas            180e6
s_sat_pri            80e6      Eq. (11)
s_sat_pyr            180e6
s_sat_pyr_ca        180e6
-----
gdot0_slip           0.001      Eqs. (1) & (2)
gdot0_twin           0.001
n_slip               50.0
n_twin               50.0
-----
h0_bas               60e6
h0_pri               60e6      Eq. (10)
h0_pyr               600e6
h0_pyr_ca            600e6
-----
h0_tw                0.0
h0_tw_sl             0.0      Eqs. (13) & (14)
-----
twinC                25
twinB                2
s_pr                 100e6      Eqs. (10) & (11)
-----
twinD                0.0
twinE                0.0      Eqs. (13) & (14)

# self and latent hardening coefficients

SlipSlip_hardening_coefficients 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0
SlipTwin_hardening_coefficients 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0
TwinSlip_hardening_coefficients 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0
TwinTwin_hardening_coefficients 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.0

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Figure 1: Example of phenomenological modelling parameters.

- The sequence for latent hardening coefficients in Figure 1 (I need to implement this part if we agree to do this way.)
 - SlipSlip_hardening_coefficients (11 types); interacting between pairs listed below
 - * self-hardening, basal-basal, prism-prism, pyr<a>-pyr<a>, pyr<c+a>-pyr<c+a>, basal-prism, basal-pyr<a>, basal-pyr<c+a>, prism-pyr<a>, prism-pyr<c+a>
 - SlipTwin_hardening_coefficients (16 types) and TwinSlip_hardening_coefficients (16 types); the sequence is the same as numbering in Tables 3 and 4. Numbers are 1 to 16.

- TwinTwin_hardening_coefficients (11 types); interacting between pairs listed below
 - * self-hardening, T1-T1, C1-C1, T2-T2, C2-C2, T1-C1, T1-T2, T1-C2, C1-T2, C1-C2, T2-C1

References

- [1] A.A. Salem, S.R. Kalidindi, and S.L. Semiatin. Strain hardening due to deformation twinning in [alpha]-titanium: Constitutive relations and crystal-plasticity modeling. *Acta Materialia*, 53(12):3495 – 3502, 2005.
- [2] Xianping Wu, Surya R. Kalidindi, Carl Necker, and Ayman A. Salem. Prediction of crystallographic texture evolution and anisotropic stress-strain curves during large plastic strains in high purity [alpha]-titanium using a taylor-type crystal plasticity model. *Acta Materialia*, 55(2):423 – 432, 2007.